

SMARC[®] conga-SMX8-Plus

SMARC[®] 2.1.1 module based on the NXP[®] i.MX 8M Plus applications processors

User's Guide

Revision 0.1 (**Preliminary**)

Revision History

| Revision | Date (yyyy-mm-dd) | Author | Changes |
|----------|-------------------|--------|---------------------------------------------------------------------|
| 0.1 | 2021-12-17 | BEU | <ul style="list-style-type: none">Preliminary release |

Preface

This user's guide provides information about the components, features and connectors available on the conga-SMX8-Plus. It is one of five documents that should be referred to when designing a SMARC® application.

The other reference documents that should be used include the following:

conga-SMX8-Plus Pinout Description (https://git.congatec.com/arm-nxp/imx8-family/doc/cgtimx8_pinlist/tree/cgtsx8p_pinlist)

SMARC® Design Guide 2.1.1 (<https://sget.org>)

SMARC® Hardware Specification 2.1.1 (<https://sget.org>)

NXP® i.MX 8M Plus Applications Processor Datasheet for Industrial Products (www.nxp.com)

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Terminology

| Term | Description |
|------------------------|-------------------------------------------------|
| °C | Degrees Celsius |
| µA | Microamp |
| µs | Microsecond |
| A | Ampere |
| AN | Application Note |
| ARM | Advanced RISC Machine |
| AVB | Audio Video Bridging |
| BT | Bluetooth |
| CAAM | Cryptographic Acceleration and Assurance Module |
| CMOS | Complementary Metal Oxide Semiconductor |
| COM | Computer-on-Module |
| CPU | Central Processing Unit |
| CSI | Camera Serial Interface |
| CSP | Cooling Solution Passive |
| DDR | Double Data Rate |
| DDRC | Double Data Rate Controller |
| DP | DisplayPort |
| DP++ | DisplayPort Dual-Mode |
| DRAM | Dynamic Random Access Memory |
| DSI | Digital Serial Interface |
| D-SUB | D-Subminiature |
| eMMC | embedded Multi-Media Controller |
| FlexCAN | Flexible Controller Area Network |
| GB | Gigabyte |
| GbE | Gigabit Ethernet |
| GHz | Gigahertz |
| GND | Ground |
| GPIO | General-Purpose Input/Output |
| GPU | Graphics Processing Unit |
| GTps | Gigatransfers per second |
| HW | Hardware |
| HAB | High Assurance Boot |
| HSP | Heat Spreader |
| Hz | Hertz |
| I/O | Input/Output |
| I ² C (I2C) | Inter-Integrated Circuit |

| | |
|------------------------|-----------------------------------------------------|
| I ² S (I2S) | Inter-Integrated Circuit Sound |
| IEEE | Institute of Electrical and Electronics Engineers |
| JEIDA | Japan Electronic Industries Development Association |
| JTAG | Joint Test Action Group |
| KS | Key State |
| LPDDR | Low-Power Double Data Rate |
| LVDS | Low-Voltage Differential Signaling |
| Mbps | Megabits per second |
| MBps | Megabytes per second |
| MHz | Megahertz |
| mm | Millimeter |
| MMU | Memory Management Unit |
| mVpp | Millivolts Peak to Peak |
| MXM | Mobile PCI Express Module |
| NC | Not Connected |
| Nm | Newton metre |
| NXP | NeXt exPerience |
| OS | Operating System |
| OTG | On-The-Go |
| PCB | Printed Circuit Board |
| PCI Express | Peripheral Component Interconnect Express |
| PHY | Physical Layer |
| PMIC | Power Management Integrated Circuit |
| PN | Part Number |
| QSPI | Quad Serial Peripheral Interface |
| RGMI | Reduced Gigabit-Media Independent Interface |
| RS-232 | Recommended Standard 232 |
| RTC | Real-Time Clock |
| SAI | Synchronous Audio Interface |
| SD | Secure Digital |
| SDIO | Secure Digital Input Output |
| SDR | Single Data Rate |
| SDRAM | Synchronous Dynamic Random Access Memory |

| | |
|--------|-----------------------------------------------------|
| SDXC | Secure Digital eXtended Capacity |
| SGET | Standardization Group for Embedded Technologies e.V |
| SMARC | Smart Mobility ARChitecture |
| SoC | System on Chip |
| SPI | Serial Peripheral Interface |
| TBD | To Be Defined |
| UART | Universal Asynchronous Receiver-Transmitter |
| U-Boot | Universal Boot Loader |
| UHS | Ultra High Speed |
| USB | Universal Serial Bus |
| uSDHC | ultra Secured Digital Host Controller |
| V | Volt |
| Vdc | Volts direct current |
| VESA | Video Electronics Standards Association |
| W | Watt |
| Wi-Fi | Wireless Fidelity |

1 Introduction

1.1 SMARC® Concept

The Standardization Group for Embedded Technologies e.V (SGET) defined the SMARC® standard for small form factor computer modules that target applications with low power, low cost and high performance. The SMARC® connector and interfaces are optimized for high-speed communication, and are suitable for ARM SoCs and low power x86 SoCs.

The SMARC® standard bridges the gap between the COM Express® standard and the Qseven® standard by offering most of the interfaces defined in the COM Express® specification at a lower power. With a footprint of 82 mm x 50 mm or 82 mm x 80 mm, the SMARC® standard promotes the design of highly integrated, energy efficient systems.

Due to its small size and lower power demands, PC appliance designers can design low cost devices as well as explore a huge variety of product development options—from compact space-saving designs to fully functional systems. This solution allows scalability, product diversification and faster time to market.

1.2 conga-SMX8-Plus

The conga-SMX8-Plus is a Computer On Module (COM) based on the SMARC® Hardware Specification 2.1.1. The conga-SMX8-Plus features an NXP® i.MX 8M Plus applications processor with four Arm® Cortex®-A53 cores and an integrated 2.3 TOPS Neural Processing Unit (NPU) for machine learning applications. The System on Chip (SoC) is manufactured using the 14nm LPC FinFET technology for high computing performance at low power. The conga-SMX8-Plus only requires 2 - 6 W @ 5V for typical applications.

By offering most of the functional requirement for any SMARC® application, the conga-SMX8-Plus provides manufacturers and developers with a platform to jump-start the development of systems and applications based on SMARC® Hardware Specification. Its features and capabilities make it an ideal platform for designing compact, energy-efficient, performance-oriented embedded systems.

1.2.1 Options Information

The conga-SMX8-Plus is available in the following variants:

Table 1 Commercial Variant

| PN | 051300 |
|----------------|--------------------------------------------------|
| NXP® Processor | i.MX 8M Plus Quad |
| Cortex®-A53 | 4x 1.8 GHz |
| SDRAM | 4 GB LPDDR4 @ 2000 MHz (32 bit) with In-line ECC |
| eMMC | 16 GB |

Table 2 Industrial Variants

| PN | 051320 | 051321 |
|----------------|--------------------------------------------------|--------------------------------------------------|
| NXP® Processor | i.MX 8M Plus Quad | i.MX 8M Plus Quad |
| Cortex®-A53 | 4x 1.6 GHz | 4x 1.6 GHz |
| SDRAM | 4 GB LPDDR4 @ 2000 MHz (32 bit) with In-line ECC | 2 GB LPDDR4 @ 2000 MHz (32 bit) with In-line ECC |
| eMMC | 16 GB | 16 GB |

1.2.2 Accessories

Table 3 Accessories

| PN | Product Name | Comments |
|----------|-----------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------|
| 48000023 | RS-232 adapter cable for conga-ARM module | Adapter cable for ARM console. MOLEX PicoBlade 6 circuit to two D-SUB 9 connector. |
| 020750 | conga-SMC1/SMARC-ARM | Compact sized 3.5" Carrier Board for ARM based SMARC 2.1 modules. |
| 007010 | conga-SEVAL | Evaluation Carrier Board for SMARC 2.1 modules. |
| 44500040 | daA4200-30mci | Camera module daA4200-30mci, Basler dart MIPI based 13MPx, 4 CSI2-Lanes, S-Mount |
| 10000399 | FFC BCON, 200mm (Basler MIPI cameras) | FFC cable to connect conga-SMC1 with MIPI camera |
| 10000428 | Evetar Lens M13B0618W F1.8 f6mm 1/3", IR-cut filter | Evetar S-mount lens with a fixed focal length of 6 mm and a fixed F-stop of F1.8. With IR-cut filter. (dedicated for Basler dart camera PN 44500040) |

2 Specifications

2.1 Feature List

| | |
|-----------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Form Factor | SMARC® Hardware Specification 2.1.1 |
| SoC | NXP® i.MX 8M Plus Quad: 4x Arm® Cortex®-A53 cores @ 1.8 GHz (commercial) or 1.6 GHz (industrial) 1x Arm® Cortex®-M7 @ 800MHz NPU 2.3 TOPS GPU GC7000UL |
| DRAM | Up to 6 GByte onboard LPDDR4 memory 4000 MT/s inline ECC |
| Ethernet | 2x Gbit Ethernet with IEEE 1588 Support (1x with TSN support) |
| I/O Interfaces | 1x dual-role USB 2.0 2x USB 2.0 2x USB 3.0 1x SDIO 3.0 1x PCIe 3.0 2x I ² C 1x SPI 3x UART (2x with Handshake) 2x CAN FD 14x GPIO 1x optional soldered M.2 1216 Wi-Fi/BT |
| Mass Storage | eMMC5.1 up to 128 GByte SPI Flash 64Mbit (Uboot) |
| Sound | 2x I ² S HiFi 4 DSP |
| Graphics | Integrated in SoC GC7000UL3D graphics with 2 high performance vec4 shaders GC520L 2D graphic supports up to 2x1080p60 or 1x4kp30 display resolution Up to 3 independent displays VPU up to 1080p60 H.265/H.264 decoding and encoding OpenGL ES 3.1 Vulkan® extensions OpenCL 1.2 FP OpenVG 1.1 |
| Video Interfaces | 1x dual channel 24-bit LVDS 1x HDMI® 2.0a 1x MIPI DSI 4-lane shared with second LVDS channel 2x MIPI-CSI 2x integrated Image Signal Processor (ISP) for cameras with up to 12 MP resolution |
| Features | Watchdog Timer Cortex-A53 Console optional JTAG debug interface High Precision Real Time Clock |
| AI & Machine Learning | Neural Processing Unit (NPU) with up to 2.3 TOP/s NXP eIQML SW tools and libraries |
| Security | Cryptographic Acceleration and Assurance Module Resource Domain Controller ARM® TrustZone® High Assurance Boot support SHE, Encryption Engine AES-128/192/256, DES/3DES, RC4, RSA4096, TRNG SHA-1/224/256 RSA-1024, 2048, 3072, 4096 and secure key storage side channel attack resistance |
| Boot Loader | U-Boot |
| Operating Systems | Linux, Yocto Project Android |
| Power Consumption | Low power Cortex-A53 / Cortex-M7 typ. application 2-6W @ 5V |
| Temperature Range | Operating Temperature Range: 0 to +60°C commercial grade -40 to +85°C industrial grade Storage Temperature Range: -40 to +85°C |
| Humidity | Operating: 10 -90% r. H. non cond. Storage: 5 -95% r. H. non cond. |
| Size | 82 x 50 mm (3,23" x 1,97") |

2.2 Supported Operating Systems

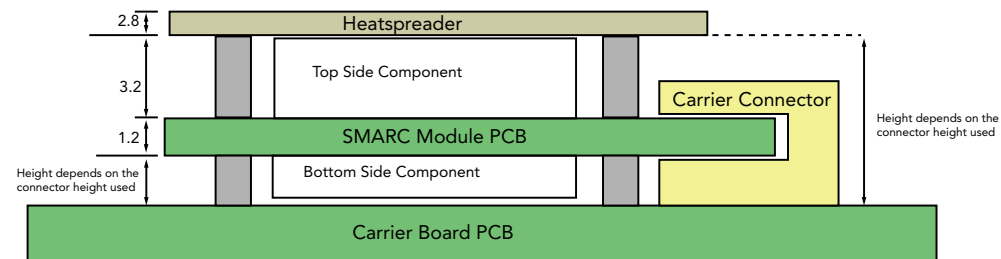
The conga-SMX8-Plus supports the following operating systems:

- Linux® (Yocto Project®)
- Android™

2.3 Mechanical Dimensions

- 82.0 mm x 50.0 mm

The height of the module, heatspreader and stack is shown below:

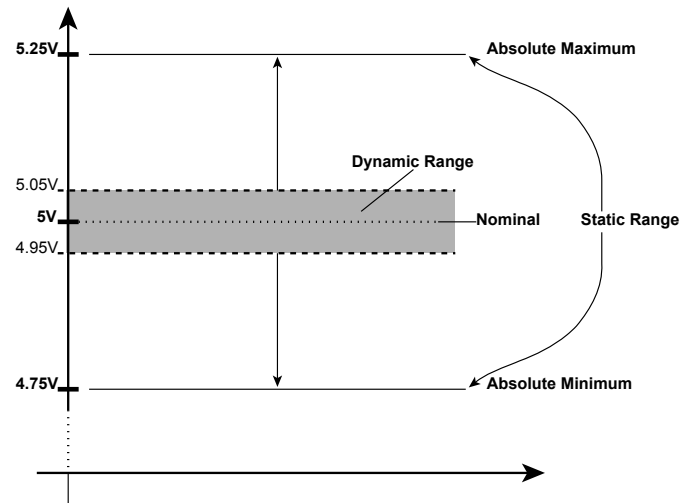


All dimensions are in millimeters

2.4 Standard Power

2.4.1 Supply Voltage

- 4.75 V – 5.25 V



2.4.2 Electrical Characteristics

| Characteristics | | | Min. | Typ. | Max. | Units | Comment |
|-----------------|---------|------|------|------|------|------------------|----------|
| 5V | Voltage | ± 5% | 4.75 | 5.00 | 5.25 | V _{dc} | |
| | Ripple | | - | - | ± 50 | mV _{PP} | 0-20 MHz |

2.4.3 Rise Time

The input voltages shall rise from 10 percent of nominal to 90 percent of nominal at a minimum slope of 250 V/s. The smooth turn-on requires that, during the 10 percent to 90 percent portion of the rise time, the slope of the turn-on waveform must be positive.

2.5 Power Consumption

The power consumption values were measured with the following setup:

- Input voltage +5 V
- conga-SMX8-Plus
- conga-SEVAL carrier board
- conga-SMX8-Plus cooling solution

The power consumption values were recorded during the system states described in the table below.

Table 4 Measurement Description

| System State | Description | Comment |
|------------------------|-----------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Suspend | Dormant mode / Deep sleep mode | For more information about these states, refer to the Application Note "i.MX 8M Plus Power Consumption Measurement" available at the NXP® website www.nxp.com . |
| Idle | System idle mode | |
| 100% Workload | 100% CPU workload | The CPU was stressed to its maximum frequency. |
| Peak Power Consumption | 100% CPU workload at approximately 100°C peak power consumption | Consider this value when designing the system's power supply to ensure that sufficient power is supplied during worst case scenarios. |



The peripherals did not influence the measured values because they were powered externally.

The table below provides the power consumption values of each conga-SMX8-Plus variant during different operating modes:

Table 5 Power Consumption Values

| PN | Memory Size | HW Revision | U-Boot | SoC | Current (A) @ 5 V | | | |
|--------|-------------|-------------|--------|-----------------------------|-------------------|------|---------------|------------------------|
| | | | | | Suspend | Idle | 100% Workload | Peak Power Consumption |
| 051300 | 4 GB | TBD | TBD | i.MX 8M Plus Quad (1.8 GHz) | TBD | TBD | TBD | TBD |
| 051320 | 4 GB | TBD | TBD | i.MX 8M Plus Quad (1.6 GHz) | TBD | TBD | TBD | TBD |
| 051321 | 2 GB | TBD | TBD | i.MX 8M Plus Quad (1.6 GHz) | TBD | TBD | TBD | TBD |

2.6 Supply Voltage Battery Power

Table 6 CMOS Battery Power Consumption

| RTC @ | Voltage | Current |
|-------|---------|-------------|
| -10°C | 3V DC | TBD μ A |
| 20°C | 3V DC | TBD μ A |
| 70°C | 3V DC | TBD μ A |



Note

1. Do not use the CMOS battery power consumption values listed above to calculate CMOS battery lifetime.
2. Measure the CMOS battery power consumption in your customer specific application in worst case conditions (for example, during high temperature and high battery voltage).
3. Consider the self-discharge of the battery when calculating the lifetime of the CMOS battery. For more information, refer to application note AN9_RTC_Battery_Lifetime.pdf on congatec website at www.congatec.com/support/application-notes

2.7 Environmental Specifications

| | | |
|-----------------------------------|-------------------------|------------------------|
| Temperature (commercial variants) | Operation: 0° to 60°C | Storage: -40° to +85°C |
| Temperature (industrial variants) | Operation: -40° to 85°C | Storage: -40° to +85°C |
| Humidity | Operation: 10% to 90% | Storage: 5% to 95% |



Caution

1. The above operating temperatures must be strictly adhered to at all times. When using a congatec heatspreader, the maximum operating temperature refers to any measurable spot on the heatspreader's surface.
2. Humidity specifications are for non-condensing conditions.

3 Block Diagram



* Assembly Option
 ** Shared with Console
 *** Shared with M7

4 Cooling Solutions

congatec GmbH offers the following cooling solutions for the conga-SMX8-Plus variants. The dimensions of the cooling solutions are shown in the sub-sections. All measurements are in millimeters.

Table 7 Cooling Solution Variants

| Cooling Solution | PN | Description |
|------------------|--------|----------------------------------------------------------------------------------------------------|
| CSP | 051350 | Passive cooling solution for SMARC module conga-SMX8-Plus. All standoffs are with 2.7mm bore hole. |
| HSP | 051351 | Heat spreader solution for SMARC module conga-SMX8-Plus. All standoffs are with 2.7mm bore hole. |
| CSA-Adapter | 050060 | Active cooling solution adapter for SMARC modules used in combination with module heat spreader. |



Note

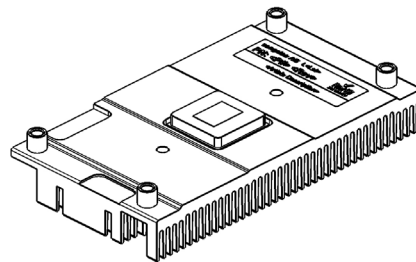
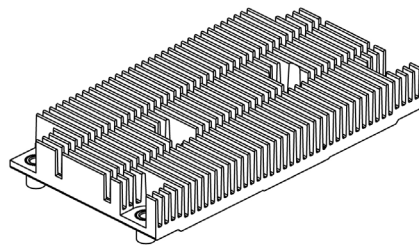
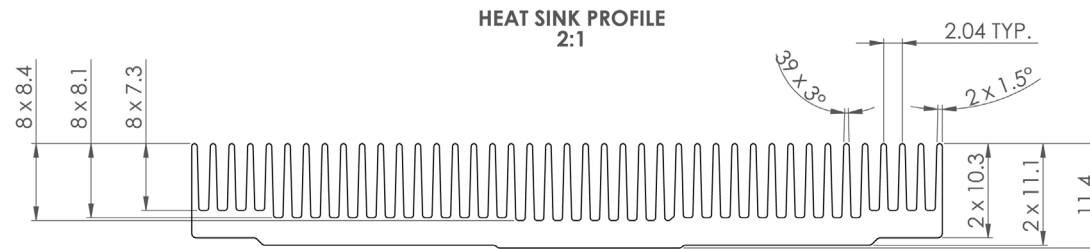
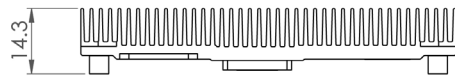
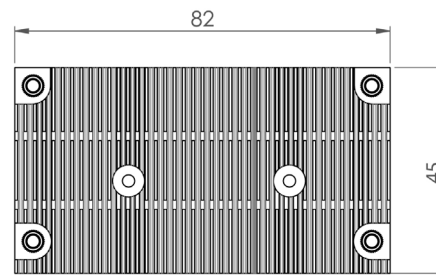
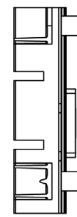
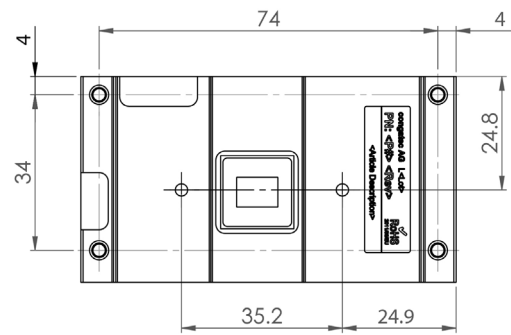
1. We recommend a maximum torque of 0.4 Nm for carrier board and module mounting screws.
2. The gap pad material used on congatec heatspreaders may contain silicon oil that can seep out over time depending on the environmental conditions it is subjected to. For more information about this subject, contact your local congatec sales representative and request the gap pad material manufacturer's specification.



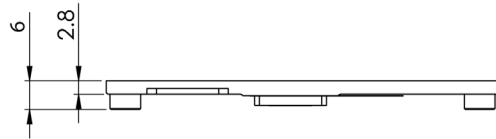
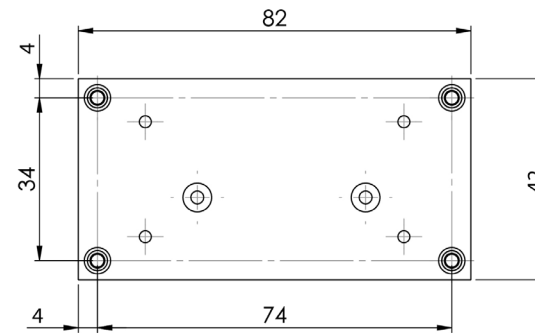
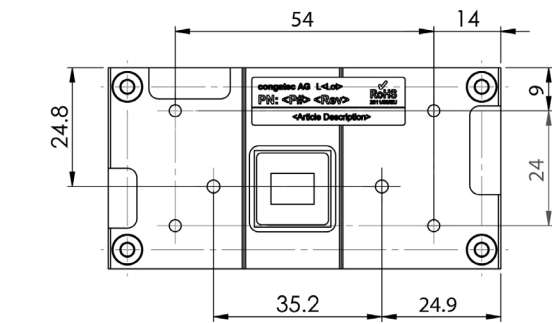
Caution

1. The congatec heatspreaders/cooling solutions are tested only within the commercial temperature range of 0° to 60°C. Therefore, if your application that features a congatec heatspreader/cooling solution operates outside this temperature range, ensure the correct operating temperature of the module is maintained at all times. This may require additional cooling components for your final application's thermal solution.
2. For adequate heat dissipation, use the mounting holes on the cooling solution to attach it to the module. Apply thread-locking fluid on the screws if the cooling solution is used in a high shock and/or vibration environment. To prevent the standoff from stripping or cross-threading, use non-threaded carrier board standoffs to mount threaded cooling solutions.
3. For applications that require vertically-mounted cooling solution, use only coolers that secure the thermal stacks with fixing post. Without the fixing post feature, the thermal stacks may move.
4. Do not exceed the recommended maximum torque. Doing so may damage the module or the carrier board, or both.

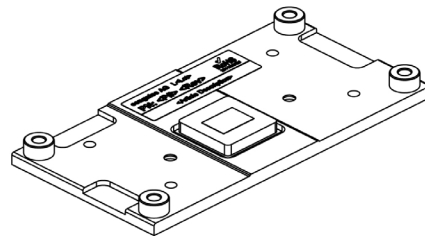
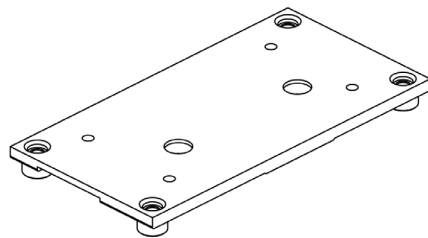
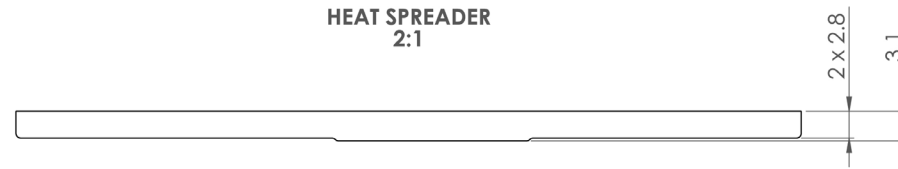
4.1 CSP Dimensions



4.2 HSP Dimensions



HEAT SPREADER
2:1



5 Connector Rows

The conga-SMX8-Plus has 314 edge fingers that mate with the MXM3 connector located on the carrier board. This connector is able to interface the signals of the conga-SMX8-Plus with the carrier board peripherals.

5.1 Display Interfaces

The conga-SMX8-Plus supports up to three independent displays as shown in the table below:

Table 8 Display Combinations

| | Display 1 | | Display 2 | | Display 3 | |
|-----------------|---------------------|-----------------|-----------|-----------------|-----------|-----------------|
| | Interface | Max. Resolution | Interface | Max. Resolution | Interface | Max. Resolution |
| Default | Dual channel LVDS | 1920x1080p60 | - | - | HDMI® | 3840x2160p30 |
| Assembly Option | Single channel LVDS | 1280x720p60 | MIPI DSI® | 2560x1080p60 | HDMI® | 3840x2160p30 |



Note

The MIPI® DSI interface only supports max. resolution 2560x1080p60 if it is the only display interface in use. Otherwise, the MIPI® DSI interface supports max. resolution 1920x1200p60 (MIPI® DSI + LVDS/HDMI®) or 1920x1080p60 (MIPI® DSI + LVDS + HDMI®).

5.1.1 LVDS / MIPI® DSI

The conga-SMX8-Plus offers LVDS[0:1] pins for one 18 / 24 bit dual channel LVDS interface by default.

Optionally, the LVDS1 pins can be used as DSI1 pins for one 4-lane MIPI DSI® interface instead as defined in the SMARC® Hardware Specification (assembly option).



Note

The conga-SMX8-Plus does not support eDP™.

5.1.2 HDMI®

The conga-SMX8-Plus offers HDMI pins for one HDMI® 2.0a display interface with support for multi-channel audio output.



Note

The conga-SMX8-Plus does not support DisplayPort++™ (DP++™).

5.2 Camera Interface (MIPI CSI-2®)

The conga-SMX8-Plus offers CSI[0:1] pins for up to two MIPI CSI-2® camera interfaces by default:

- CSI0 offers two lanes (up to 1.5 Gbps/lane)
- CSI1 offers four lanes (up to 1.5 Gbps/lane)

Optionally, the conga-SMX8-Plus can offer an onboard connector for Basler's proprietary BCON for MIPI interface with four lanes instead of CSI0 with two lanes (assembly option).



Note

For camera accessories, refer to section 1.2.2 "Accessories".

5.3 SDIO Card (4 bit) Interface

The conga-SMX8-Plus offers pins for one SD card / SDIO interface. This interface supports:

- OS boot (Optionally, also bootcontainer)
- SD/SDIO specification 3.0
- 200 MHz 1.8V signaling for up to 100 MBps
- Secure Digital eXtended Capacity (SDXC™) cards
- UHS-I (SDR104/50 and DDR50) ¹
- Default Mode and High Speed Mode



Note

¹ *The conga-SEVAL evaluation carrier board only supports UHS-I with full-size SD cards. Adapters (microSD to SD) are not supported.*

5.4 SPI

The conga-SMX8-Plus offers SPI0 pins for one Serial Peripheral Interface (SPI) with two device chip selects via the SPI0_CS[0:1]# pins. The max. supported clock frequency for read operations is 25 MHz and 50 MHz for write operations. SPI0 is connected to ECSPi2 of the SoC.

Optionally, the conga-SMX8-Plus can offer SPI1 pins for an additional SPI interface instead of SER2 pins (assembly option). For more information, see section 5.7 "Serial Ports". With this assembly option, SPI1 is connected to ECSPi1 of the SoC.

Optionally, the conga-SMX8-Plus can offer SPI1 pins for an additional SPI instead of the onboard NOR SPI flash memory chip (assembly option). For more information, see section 6.3 "SPI NOR Flash". With this assembly option, SPI1 is connected to QSPiA of the SoC.



Note

The conga-SMX8-Plus does not support eSPI.

5.5 Audio (I2S)

The conga-SMX8-Plus offers I2S0 and I2S2 pins for two Inter-IC Sound (I²S) buses by default:

- I2S0 is connected to SoC SAI2
- I2S2 is connected to SoC SAI3

Optionally, the I2S0 signals can be connected to the optional onboard Wi-Fi/BT module instead of the SMARC[®] connector (assembly option).



Note

The conga-SMX8-Plus does not support HDA.

5.6 I2C Interfaces

The conga-SMX8-Plus offers the Inter-Integrated Circuit (I²C) buses as defined in the SMARC[®] Hardware Specification. The buses support the recommended multi-master capability and data rates of 100 kHz and 384 kHz.

- The I2C_PM bus (SoC I2C2) is shared with SMARC[®] LVDS/DSI DDC and CSI0/2 interfaces.
- The I2C_GP bus (SoC I2C3) is shared with the SMARC[®] CSI1 interface.



Note

All devices must have a unique I²C address.

5.7 Serial Ports

The conga-SMX8-Plus offers SER[0:2] pins for three asynchronous serial ports by default. Each port supports programmable baud rates of up to 4 Mbps. SER0 and SER2 support handshaking. Optionally, the conga-SMX8-Plus can offer:

- Arm® Cortex®-M7 debug interface via onboard connector X2 instead of SER1 (assembly option)
- SPI1 pins for an additional SPI interface instead of SER2 pins (assembly option)
- Wi-Fi/BT module instead of the SMARC® SER2 pins (assembly option)

5.8 CAN Bus

The conga-SMX8-Plus offers CAN[0:1] pins for two Controller Area Network (CAN) buses via two FlexCAN controllers integrated in the SoC. Each bus supports the CAN FD and CAN 2.0 B protocols.

5.9 USB Interfaces

The conga-SMX8-Plus offers USB[0:4] pins for five USB ports by default. The USB[1:4] pins are provided via a TI TUSB8041 USB hub. USB0 is directly routed to the SoC. ¹

Optionally, the conga-SMX8-Plus can be offered without the USB hub (assembly option). The USB signals from the SoC can be directly routed to the SMARC® USB3 pins.

Table 9 USB Interfaces - Default and Options Description

| SMARC | Default | Assembly Option (Without USB Hub) |
|-------------------|-------------------|--------------------------------------|
| USB0 ¹ | USB 2.0 Dual-Role | USB 2.0 Dual-Role |
| USB1 | USB 2.0 | N/A |
| USB2 | USB 3.0 (5 Gbps) | N/A |
| USB3 | USB 3.0 (5 Gbps) | USB 3.0 (5 Gbps) |
| USB4 | USB 2.0 | N/A |



Note

¹ USB0 can be used for the Serial Downloader mode. For more information, see FORCE_RECOV# description in section 5.13 "Boot Select".

5.10 PCI Express®

The conga-SMX8-Plus offers PCIE_A pins for one PCIe® x1 Gen 3 bus with a bitrate of up to 8 GTps by default.

The conga-SMX8-Plus offers an onboard precision oscillator (DSC557-03) that generates the reference clock for PCIE_A (PCIE_A_REFCK±) by default. Alternatively, the SoC clock generator can be used instead.

Optionally, the SoC PCIe interface can be connected to the optional onboard WiFi/BT module instead of SMARC® PCIE_A (assembly option).

5.11 Ethernet

The conga-SMX8-Plus offers GBE[0:1] pins for two ethernet interfaces via two onboard TI DP83867IS Physical Layers (PHYs). Both interfaces support:

- 10/100/1000 Mbps
- Energy Efficient Ethernet (EEE)
- Ethernet AVB
- IEEE 1588v2 Precision Timing Protocol (PTP)

In addition, GBE0 also supports Time Sensitive Networking (TSN).

5.12 GPIO

The conga-SMX8-Plus offers GPIO[0:13] pins for 14 GPIOs. All pins are capable of bi-directional operation and are pulled up to 1.8V via SoC internal 22k pull-up resistors. Several GPIOs can be used for alternative functions as defined in the SMARC® Hardware Specification.

Table 10 GPIO[0:13] Pinout Description

| Signal Name | Pin | Description | PU / PD | Alternative Use |
|-------------|------|-----------------------------|-----------|---------------------------|
| GPIO0 | P108 | GPIO Pin 0 Preferred Output | socPU-22k | CAM0_PWR# |
| GPIO1 | P109 | GPIO Pin 1 Preferred Output | socPU-22k | CAM1_PWR# |
| GPIO2 | P110 | GPIO Pin 2 Preferred Output | socPU-22k | CAM0_RST# |
| GPIO3 | P111 | GPIO Pin 3 Preferred Output | socPU-22k | CAM1_RST# |
| GPIO4 | P112 | GPIO Pin 4 Preferred Output | socPU-22k | HDA_RST# is not supported |
| GPIO5 | P113 | GPIO Pin 5 Preferred Output | socPU-22k | PWM_OUT |
| GPIO6 | P114 | GPIO Pin 6 Preferred Input | socPU-22k | TACHIN is not supported |
| GPIO7 | P115 | GPIO Pin 7 Preferred Input | socPU-22k | |
| GPIO8 | P116 | GPIO Pin 8 Preferred Input | socPU-22k | |
| GPIO9 | P117 | GPIO Pin 9 Preferred Input | socPU-22k | |
| GPIO10 | P118 | GPIO Pin 10 Preferred Input | socPU-22k | |
| GPIO11 | P119 | GPIO Pin 11 Preferred Input | socPU-22k | |
| GPIO12 | S142 | GPIO Pin 12 Preferred Input | socPU-22k | |
| GPIO13 | S123 | GPIO Pin 13 Preferred Input | socPU-22k | |



Note

The conga-SMX8-Plus does not support HDA_RST# and TACHIN.

5.13 Boot Select

The bootcontainer source can be selected via BOOT_SEL[2:0]# as described in the table below: ¹

| BOOT_SEL | | | Selected Boot Source |
|----------|--------|--------|----------------------------------------|
| 0# | 1# | 2# | |
| Float | Float | Float | SPI Flash eFuse (default) ² |
| Float | Ground | Ground | SPI Flash |
| Ground | Ground | Float | SD card |
| Float | Ground | Float | eMMC |
| Ground | Float | Float | Serial Download Mode ³ |

On the conga-SEVAL evaluation carrier board, the boot source can be selected via DIP switches M17 and M18 as described in the table below:

| M17 | | M18 | Selected Boot Source |
|-----|-----|-----|----------------------------------------|
| #1 | #2 | #1 | |
| OFF | OFF | OFF | SPI Flash eFuse (default) ² |
| OFF | ON | ON | SPI Flash |
| ON | ON | OFF | SD card |
| OFF | ON | OFF | eMMC |
| ON | OFF | OFF | Serial Download Mode ³ |

The OS boot device is defined via the U-Boot environment variables. For more information, refer to the conga-SMX8-Plus online software documentation at <https://wiki.congatec.com>



Note

- ¹ The available boot sources and their selection via BOOT_SEL[2:0]# pins correspond with the boot mode options and configuration pins defined by NXP®. Therefore, select the desired boot source according to this table instead of the SMARC® Hardware Specification.
- ² Bootcontainer in onboard SPI Flash. eFuses select FlexSPI.
- ³ The Serial Download Mode can also be selected via the FORCE_RECOV# pin. For normal operation, ensure this pin is not low.

FORCE_RECOV#

Low on the FORCE_RECOV# pin enables the Serial Download Mode regardless of the selected boot source via the BOOT_SEL[2:0]# pins. For normal operation, ensure this pin is not low. The program image can be downloaded over the USB0 port (see section 5.9 "USB Interfaces"). On the conga-SEVAL evaluation carrier board, set the jumper X45 to position 2-3 to enable the Serial Download Mode. For normal operation, ensure the jumper X45 is set to the default position 1-2.

5.14 Power Control

The power-up sequence of the conga-SMX8-Plus is described below:

1. The carrier board provides the input voltage (VDD_IN) to the module.
2. If VIN_PWR_BAD# is not driven low, the module enables its power circuits.
3. After the first VIN power on, the module starts the power-up sequence.
4. The module enables the carrier board power by asserting CARRIER_PWR_ON (SUS_S5#) and CARRIER_STBY# (SUS_S3#).
5. The module releases RESET_OUT# and starts the boot process.
6. RESET_IN# can be used for postpone boot process.

VIN_PWR_BAD#

VIN_PWR_BAD# (pin S150) is an active-low input signal. It indicates that the input voltage to the module is either not ready or out of specified range. Carrier board hardware should drive this signal low until the input power is up and stable. Releasing VIN_PWR_BAD# too early can cause numerous boot up problems. The module has a 10k pull up resistor to VDD_IN.

CARRIER_PWR_ON

CARRIER_PWR_ON (pin S154) is an active-high output signal. The module asserts this signal to enable power supplies for devices connected to the carrier board.

CARRIER_STBY#

The CARRIER_STBY# signal (pin S153) is an active-low output that can be used to indicate that the module is going into suspend state, where the A53 core power is turned off.

RESET_IN#

The RESET_IN# signal (pin P127) is an active-low input signal from the carrier board. The signal may be used to force the module to reset.

RESET_OUT#

The RESET_OUT# signal (pin P126) is an active-low output signal from the module. The module asserts this signal during the power-up sequencing to allow the carrier board power circuits to come up. The module deasserts this signal to begin the boot-up process.

POWER_BTN#

The POWER_BTN# (pin P128) is an active-low power button input from the carrier board. This power button signal is used to wake the system. Driving this signal low for at least 5 seconds powers off the system immediately.

Power Supply Implementation Guidelines

The operational power source for the conga-SMX8-Plus is 5 V. The remaining necessary voltages are internally generated on the module with onboard voltage regulators.

A carrier board designer should be aware of the important information below when designing a power supply for a conga-SMX8-Plus application:

- We have noticed that on some occasions, problems occur when using a 5 V power supply that produces non monotonic voltage when powered up. The problem is that some internal circuits on the module (e.g. clock-generator chips) generate their own reset signals when the supply voltage exceeds a certain voltage threshold. A voltage dip after passing this threshold may lead to these circuits becoming confused, thereby resulting in a malfunction. This problem though rare, has been observed in some mobile power supply applications. The best way to ensure that this problem is not encountered is to observe the power supply rise waveform through an oscilloscope. This will help to determine if the rise is indeed monotonic and does not have any dips. You should do this during the power supply qualification phase to ensure that the problem does not occur in the application. For more information, see the “Power Supply Design Guide for Desktop Platform Form Factors” document at www.intel.com.

Inrush and Maximum Current Peaks on VDD_IN

The maximum peak-current on the conga-SMX8-Plus VDD_IN (5 V) power rail can be as high as TBD A for a maximum of TBD μ s. You should therefore ensure the power supply and decoupling capacitors provide enough power to drive the module.



For more information about power control event signals, refer to the SMARC® Hardware Specification.

6 Onboard Interfaces and Devices

6.1 DRAM

The conga-SMX8-Plus offers up to 6 GB 32 bit LPDDR4 onboard SDRAM @ 2000 MHz with support for In-band ECC. The memory size of each conga-SMX8-Plus variant is listed in section 1.2.1 "Options Information".

6.2 eMMC

The conga-SMX8-Plus offers an onboard eMMC 5.1 HS400 storage device with up to 128 GB (16 GB assembled by default). Changes to the onboard eMMC may occur during the lifespan of the module in order to keep up with the rapidly changing eMMC technology. The performance of the newer eMMC may vary depending on the eMMC technology.



Note

For adequate operation of the eMMC, ensure that at least 15 % of the eMMC storage is reserved for vendor-specific functions.

6.3 SPI NOR Flash

The conga-SMX8-Plus offers an onboard SPI NOR flash memory chip with up to 256 Mbit (64 Mbit assembled by default). The SPI NOR flash memory chip is connected via QSPI by default. Optionally, the conga-SMX8-Plus can offer SPI1 pins for an additional SPI instead of the onboard NOR SPI flash memory chip (assembly option).

6.4 Wi-Fi and Bluetooth

Optionally, the conga-SMX8-Plus can offer Wi-Fi and Bluetooth connectivity via an onboard Azure Wave AW-CM276NF 802.11 a/b/g/n/ac 2x2+BT5.0 or Azure Wave AW-NM191NF 802.11 b/g/n 1x1 M.2 1216 module (assembly option).

We recommended to connect this module via an SDIO interface of the SoC. However, it is possible to connect the module via interfaces that are routed to the SMARC® connector by default:

- PCI Express (instead of PCIE_A)
- USB (instead of USB4)
- Serial Port (instead of SER2; can only be used for Bluetooth)

Optionally, SoC SAI2 signals can be connected to this module (assembly option). For more information, see section 5.5 "Audio (I2S)".

6.5 RTC

The conga-SMX8-Plus offers a discrete Real-Time Clock (RTC) via an onboard MicroCrystal RV-4162-C7 module (I²C Address: 0xD0). This RTC module is powered via the SMARC[®] VDD_RTC rail or a 3.3V rail.



Note

The conga-SMX8-Plus has onboard Schottky diodes that prevent reverse current.

6.6 Console and Debug Interfaces

6.6.1 A53 Console and M7 Debug

The conga-SMX8-Plus offers an Arm[®] Cortex[®]-A53 console interface via the onboard connector X2.

Optionally, the conga-SMX8-Plus can also offer an Arm[®] Cortex[®]-M7 debug interface on this connector shared with SMARC[®] SER1 pins.

The connector pinout is described in the table below:

Table 11 A53 and Optional M7 Connector (X2) Pinout Description

| Pin | SoC Ball | Description |
|-----|-----------|---------------------------------------------------------------------------------------------------------|
| 1 | UART4_TXD | M7 Debug: Transmit signal via ISL3243E RS-232 Transmitter/Receiver connected to UART4_TXD of the SoC |
| 2 | +VIN | SMARC VDD_IN (+5 V) |
| 3 | GND | Ground |
| 4 | UART2_TXD | A53 Console: Transmit signal via ISL3243E RS-232 Transmitter/Receiver connected to UART2_TXD of the SoC |
| 5 | UART2_RXD | A53 Console: Receive signal via ISL3243E RS-232 Transmitter/Receiver connected to UART2_RXD of the SoC |
| 6 | UART4_RXD | M7 Debug: Receive signal via ISL3243E RS-232 Transmitter/Receiver connected to UART4_RXD of the SoC |

Connector Type

X2: Molex PicoBlade 0532610671 (6 Circuits, 1.25mm Pitch, Right-Angle, Friction Lock)

Mates with Molex PicoBlade Cable Assembly Series 15134 with 6 Circuits

For a matching cable with two D-SUB 9 connectors, see PN 48000023 in Table 3.

6.6.2 JTAG Debug

Optionally, the conga-SMX8-Plus can offer an onboard JTAG debug interface (X3) (assembly option).

The connector pinout is described in the table below:

Table 12 Optional JTAG Debug Connector (X3) Pinout Description

| Pin | SoC Ball | Description |
|-----|------------|--------------------------|
| 1 | JTAG_VREF | +1.8V sourced by Module |
| 2 | JTAG_TMS | JTAG mode select |
| 3 | GND | Ground |
| 4 | JTAG_TCK | JTAG clock |
| 5 | GND | Ground |
| 6 | JTAG_TDO | JTAG data out |
| 7 | JTAG_MOD | Not connected |
| 8 | JTAG_TDI | JTAG data in |
| 9 | GND | Ground |
| 10 | JTAG_SRST# | System Reset, active low |

Connector Type

X3: Molex PicoBlade 0532611071 (10 Circuits, 1.25mm Pitch, Right-Angle)

7 Signal Descriptions and Pinout Tables

Click on the screenshot or link below to directly download the conga-SMX8-Plus pinout as an Excel file:

| X1A + X1B - SX8P SMARC edge connection | | | | | | | |
|----------------------------------------|-------------------|--------------|----------------|-----------|-----|-----------|---------------------------------------------------------------------|
| SX8P / conga-SMX8-Plus Interface | i.MX8MP Ball Name | i.MX8MP Ball | SMARC Pin Name | SMARC Pin | I/O | PU/PD | Remark |
| I2S | SAI2_MCLK | AJ15 | AUDIO_MCK | S38 | O | | |
| Management Pins | NAND_READY_B | T28 | BATLOW# | S156 | I | PU-10k | |
| Boot Select | BOOT_MODE0 | G10 | BOOT_SEL0# | P123 | I | PU-10k | via inverter, on engineering samples only |
| Boot Select | BOOT_MODE1 | F8 | BOOT_SEL1# | P124 | I | PU-10k | via inverter, on engineering samples only |
| Boot Select | BOOT_MODE2 | G8 | BOOT_SEL2# | P125 | I | PU-10k | via inverter, on engineering samples only |
| CSI Master clock output | GPIO1_IO15 | B5 | CAM_MCK | S6 | O | | |
| CAN0 | SAI5_RXD2 | AF16 | CAN0_RX | P144 | I | socPU-22k | |
| CAN0 | SAI5_RXD1 | AD16 | CAN0_TX | P143 | O | socPU-22k | |
| CAN1 | SAI5_MCLK | AF14 | CAN1_RX | P146 | I | socPU-22k | |
| CAN1 | SAI5_RXD3 | AE14 | CAN1_TX | P145 | O | socPU-22k | |
| Management Pins | PMIC_ON_REQ | F22 | CARRIER_PWR_ON | S154 | O | PD-2k2 | via buffer |
| Management Pins | PMIC_STBY_REQ | J24 | CARRIER_STBY# | S153 | O | PD-2k2 | via inverter from SOC PMIC_STBY_REQ; enabled by I2C5_PICAL6524_P2_2 |
| Management Pins | SAI1_MCLK | AE12 | CHARGER_PRSN# | S152 | I | PU-10k | |
| Management Pins | SAI5_RXC | AD14 | CHARGING# | S151 | I | PU-10k | |

https://git.congatec.com/arm-nxp/imx8-family/doc/cgtimx8_pinlist/-raw/cgtsx8p_pinlist/cgtsx8p_pin_connection.xlsx

Alternatively, you can find the conga-SMX8-Plus pinout by selecting it from the drop-down list at:

https://git.congatec.com/arm-nxp/imx8-family/doc/cgtimx8_pinlist/tree/master

The SMARC® signals are described in the SMARC® Hardware Specification publicly available at:

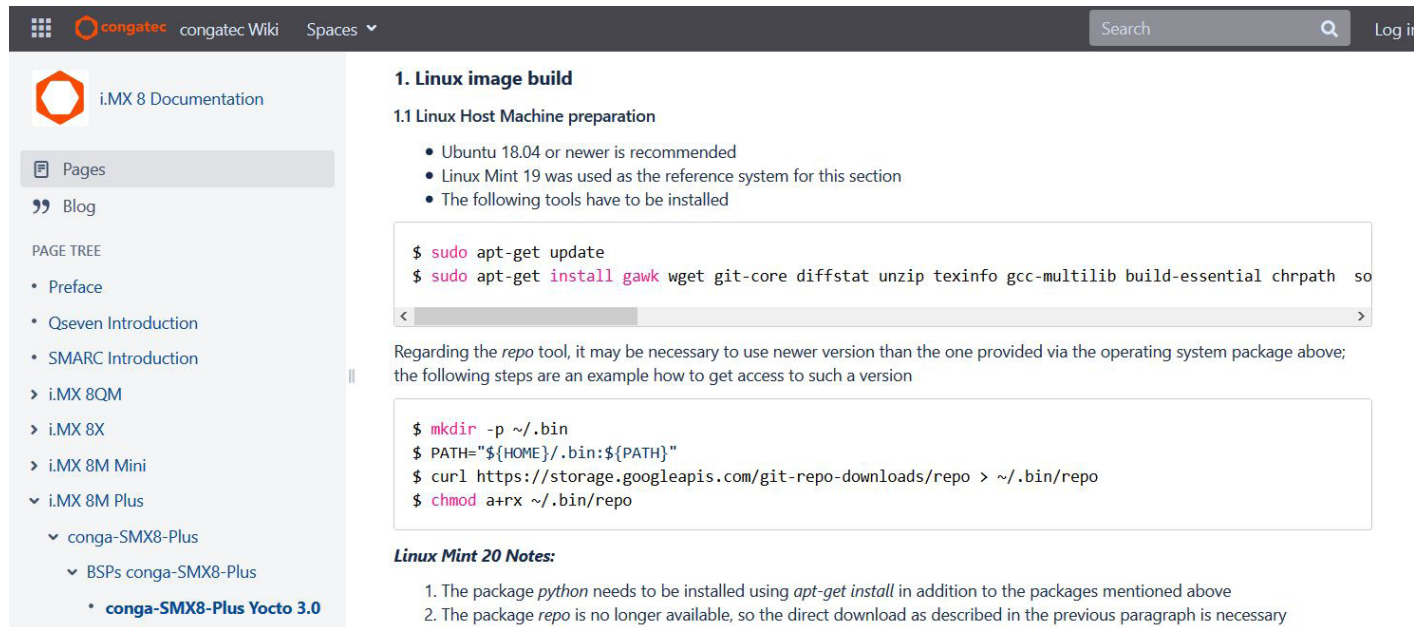
<https://sget.org>

The NXP® i.MX 8M Plus Applications Processor Datasheet for Commercial and Industrial Products is available at:

<https://www.nxp.com>

8 Software Documentation

Click on the screenshot or link below to open the conga-SMX8-Plus software documentation in your browser:



The screenshot shows a web browser displaying the Congatec Wiki page for i.MX 8 Documentation. The page title is "i.MX 8 Documentation". The left sidebar contains a navigation menu with the following items: Pages, Blog, PAGE TREE, Preface, Qseven Introduction, SMARC Introduction, i.MX 8QM, i.MX 8X, i.MX 8M Mini, i.MX 8M Plus, conga-SMX8-Plus, BSPs conga-SMX8-Plus, and conga-SMX8-Plus Yocto 3.0. The main content area is titled "1. Linux image build" and contains the following sections:

- 1.1 Linux Host Machine preparation**
 - Ubuntu 18.04 or newer is recommended
 - Linux Mint 19 was used as the reference system for this section
 - The following tools have to be installed

```
$ sudo apt-get update
$ sudo apt-get install gawk wget git-core diffstat unzip texinfo gcc-multilib build-essential chrpath so
```

Regarding the *repo* tool, it may be necessary to use newer version than the one provided via the operating system package above; the following steps are an example how to get access to such a version

```
$ mkdir -p ~/.bin
$ PATH="${HOME}/.bin:${PATH}"
$ curl https://storage.googleapis.com/git-repo-downloads/repo > ~/.bin/repo
$ chmod a+rx ~/.bin/repo
```

Linux Mint 20 Notes:

1. The package *python* needs to be installed using *apt-get install* in addition to the packages mentioned above
2. The package *repo* is no longer available, so the direct download as described in the previous paragraph is necessary

<https://wiki.congatec.com/pages/viewpage.action?pageId=9339238>

Alternatively, you can find the conga-SMX8-Plus software documentation by selecting it from the navigation menu at:

<https://wiki.congatec.com>